

MARKOV PROCESS

$$\frac{P(1 \rightarrow 2)}{P(2 \rightarrow 1)} = \frac{e^{-\beta E_2}}{e^{-\beta E_1}} = \frac{P(2)}{P(1)}$$

Microscopic definition of work heat

$$E = \sum P_i E_i$$

$$dE = \underbrace{\sum E_i dP_i}_{dQ \text{ heat}} + \underbrace{\sum P_i dE_i}_{dW \text{ work}}$$

$$\Delta E = \Delta Q + \Delta W$$

Assume (Canonical Ensemble, Temp β)

state specified by λ indexes \rightarrow $\begin{cases} i & \text{structure, state index - can change during Markov step} \\ \lambda & \text{control parameter} \rightarrow \text{changed deliberately} \end{cases}$

energy of system = $E(i_t, \lambda_t)$

where (i_t, λ_t) is state at time t .

No process were studying is

$$i_0 \xrightarrow{\lambda_0} i_1 \xrightarrow{\lambda_1} i_2 \rightarrow \dots \xrightarrow{\lambda_t} i_t$$

start with system $\downarrow E(i_0, \lambda_0)$
change λ $\downarrow E(i_0, \lambda_1)$
Markov time step $\downarrow E(i_1, \lambda_1)$

initial state i_0, λ_0
final state i_t, λ_t

t is Time of Path.

$$\Delta E = E(i_t, \lambda_t) - E(i_0, \lambda_0)$$

$$W = [E(i_1, \lambda_1) - E(i_0, \lambda_0)] + [E(i_2, \lambda_2) - E(i_1, \lambda_1)] + \dots + [E(i_t, \lambda_t) - E(i_{t-1}, \lambda_{t-1})]$$

$$= \sum_{t=0}^{t-1} [E(i_{t+1}, \lambda_{t+1}) - E(i_t, \lambda_t)] \quad \text{t terms}$$

$$Q = [E(i_1, \lambda_1) - E(i_0, \lambda_0)] + \dots + [E(i_t, \lambda_t) - E(i_{t-1}, \lambda_{t-1})]$$

$$= \sum_{t=0}^{t-1} [E(i_{t+1}, \lambda_{t+1}) - E(i_t, \lambda_t)]$$

$$W + Q = \sum_{t=0}^{t-1} \underbrace{E(i_{t+1}, \lambda_{t+1}) - E(i_t, \lambda_t)}_0 + \underbrace{E(i_{t+1}, \lambda_{t+1}) - E(i_t, \lambda_t)}_{\text{telescopes}}$$

$$= E(i_t, \lambda_t) - E(i_0, \lambda_0) = \Delta E$$

Now consider

$$\frac{P(i_0 \xrightarrow{\lambda_0} i_1 \xrightarrow{\lambda_1} i_2)}{P(i_1 \xrightarrow{\lambda_1} i_0 \xrightarrow{\lambda_0} i_1)} = \frac{P(i_0 \xrightarrow{\lambda_0} i_1) P(i_1 \xrightarrow{\lambda_1} i_2)}{P(i_1 \xrightarrow{\lambda_1} i_0) P(i_0 \xrightarrow{\lambda_0} i_1)} \dots \frac{P(i_{t-1} \xrightarrow{\lambda_{t-1}} i_t)}{P(i_t \xrightarrow{\lambda_t} i_{t-1})}$$

$$\text{But } \frac{P(i_0 \xrightarrow{\lambda_0} i_1)}{P(i_1 \xrightarrow{\lambda_0} i_0)} = \frac{e^{-\beta E(i_1, \lambda_0)}}{e^{-\beta E(i_0, \lambda_0)}}$$

$$\frac{P(\text{FORWARD PATH})}{P(\text{REVERSE PATH})} = \exp[-\beta (E(i_1, \lambda_0) - E(i_0, \lambda_0) + E(i_2, \lambda_1) - E(i_1, \lambda_1) - \dots - E(i_t, \lambda_t) + E(i_{t-1}, \lambda_{t-1}))]$$

$$= e^{-\beta \Delta Q}$$

TA DA!